
Using Swarm Intelligence in Linda Systems

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Linda

▶ The success story

- ▶ Simple
- ▶ Used as basis for commercial implementations
 - ▶ T Spaces, JavaSpaces and GigaSpaces

▶ The problems

- ▶ Lacks scalability
- ▶ Not able to adapt to changes at the application level
 - ▶ Lack of adaptiveness

We've tried!!!

Scalability Approaches

▶ Centralization

- ▶ Also called distributed central servers approach
- ▶ Easy to implement
- ▶ Carries all the disadvantages of centralized services

▶ Partitioning

- ▶ Similar tuples are placed in a set of tuple spaces servers
- ▶ May lead to unbalanced distribution of load unless a good hashing function is chosen
- ▶ Includes a level of centralization for groups of tuples
- ▶ Reconfigurations are difficult to handle

We've tried!!!

Scalability Approaches

▶ Full replication

- ▶ Places copies of tuples spaces in several nodes at different locations
- ▶ Addition and removal of tuples need to be replicated across all node
 - ▶ This is done so that searches can be performed locally
- ▶ Very high cost of keeping replicas requiring locking protocols

▶ Intermediate replication

- ▶ Grid of nodes formed by logical intersecting buses
 - ▶ Each node has one inbus and one outbus
- ▶ Data is replicated on all nodes of the outbus
- ▶ Searches are performed in the inbus
- ▶ Number of concurrent access is proportional to the number of inbuses and outbuses
- ▶ Still carries some of the cost of full replication

“Ultimate” Scalable Systems

- ▶ **Natural forming multi-agent systems**
 - ▶ Ant colonies, Termites mounds, etc.
 - ▶ Enormous in size
- ▶ **Artificial Ants**
 - ▶ Proved effective in practice
 - ▶ Optimization tool (meta-heuristic)
 - ▶ Network routing
- ▶ **Why use it in Linda?**
 - ▶ Small objects —» Tuples
 - ▶ Stigmergy —» Associative Communication
 - ▶ Mobility —» Tuples and Processes

A Bit About Swarms

- ▶ Stigmergy and Direct Communication are used

- ▶ But always local

- ▶ Random choices of path

$$P_{ij}^k(\mathbf{t}) = \frac{[\tau_{ij}(\mathbf{t})]^\alpha \cdot [\eta_{ij}]^\beta}{\sum_{l \in J_i^k} [\tau_{il}(\mathbf{t})]^\alpha \cdot [\eta_{il}]^\beta}$$

- ▶ Probability is then used to decide which path to choose
- ▶ An example of the pheromone update rule can be given by

$$\tau_{il}(t) \leftarrow (1 - \rho) \cdot \tau_{il}(t) + \Delta \tau_{il}(t)$$

Negative Feedback

Reinforcement

Concepts of SwarmLinda

▶ Ants

- ▶ Templates or tuples

▶ Environment (terrain)

- ▶ Linda system (or the set of tuple space nodes)

▶ State

- ▶ Information about the current condition of the system

▶ We wanted to be true to swarm concepts in SwarmLinda

- ▶ Simplicity
- ▶ Dynamism
- ▶ Locality

Searching for Tuples

- ▶ Tuples are food
- ▶ Templates are ants
- ▶ State is given by a tuple scent
- ▶ Tuple-space nodes are the terrain
 - ▶ maybe different for each tuple format
- ▶ The steps are as follows:
 - ▶ Spread the scent of the process
 - ▶ Check for a matching tuple at the ant's current location
 - ▶ If found return to origin dropping the scent for that template
 - ▶ If not found check neighborhood for traces of desired scent
 - ▶ If there is no scent, choose the next step randomly.
 - ▶ If there is a scent, move towards the scent location (i) with probability P_{ci} .
- ▶ So what happens after several unsuccessful steps?

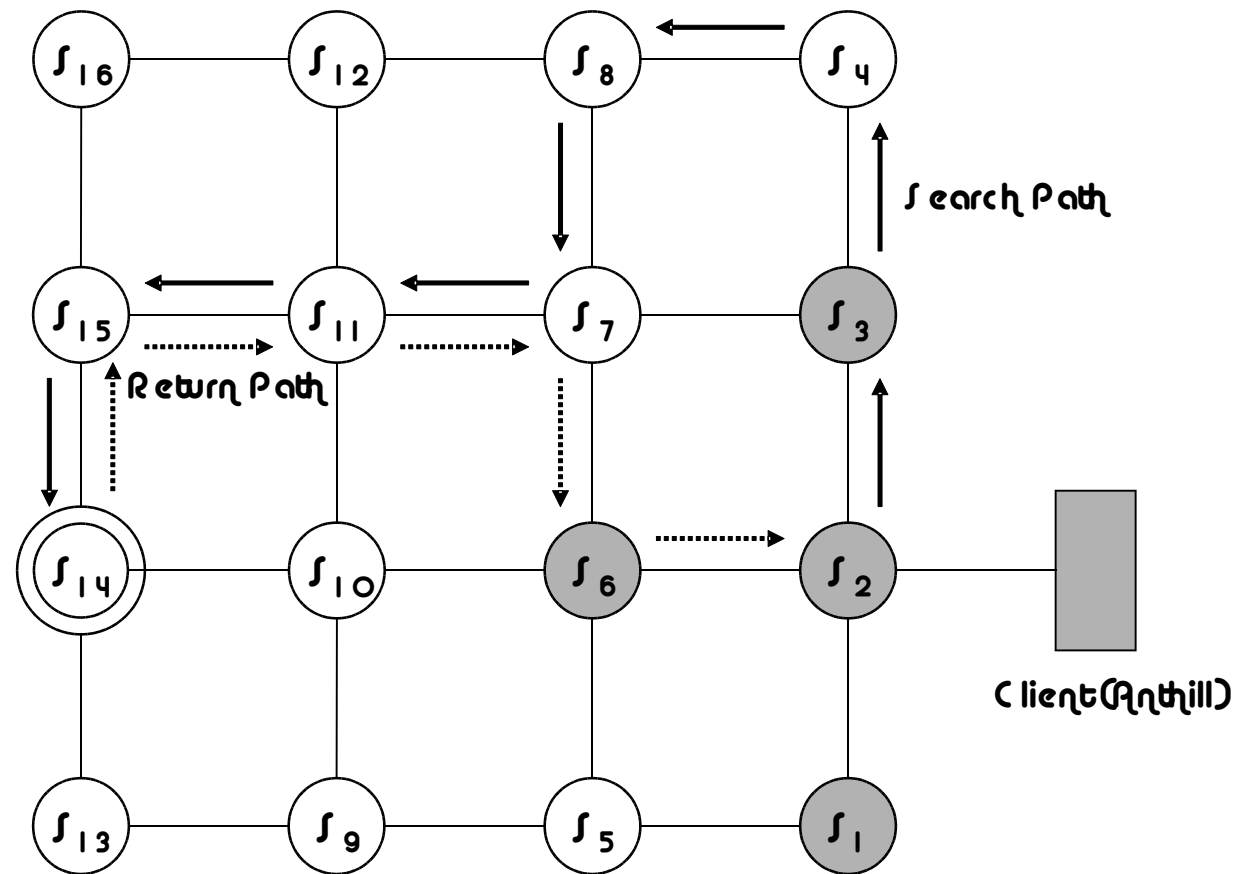
Is it Better Searching Mechanism?

- ▶ **SwarmLinda describe an emergent behavior**
 - ▶ Application specific paths are formed between tuple producers and consumers
- ▶ **The alternative is hashing-based schemes**
 - ▶ Certainly fast!
 - ▶ Not adaptive
 - ▶ Tuples always placed in the same location
 - ▶ Size of the system has no influence on the choice of location
 - ▶ Dynamic configurations are hard to handle
 - ▶ And on-the-fly factors may need to be considered when deciding where to place a tuple
 - ▶ Load balancing
 - ▶ Bottlenecks
 - ▶ Scheduled (and unscheduled) down time on the servers

Pictorial View of Searching

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Pictorial View of Searching



Distribution Mechanism

- ▶ Dynamic mechanism based on brood sorting
- ▶ Tuples are ants
- ▶ Tuple-space nodes are the terrain
- ▶ State is the set of tuples stored thus far
- ▶ The steps are as follows:
 - ▶ Starting visiting the nodes once an *out* is executed.
 - ▶ Observe the kind of tuples the nodes are storing.
 - ▶ Each out-ant has a limited memory to guarantee the decision is local
 - ▶ Store tuples if nearby nodes contain similar tuples.
 - ▶ The likelihood of storing a tuple is calculated stochastically based on the kinds of objects in memory
 - ▶ If nearby nodes don't contain similar tuples, randomly choose to drop or carry the tuple to the next node
 - ▶ An aging mechanism needs to be in place in this step

Is it a Better Distribution Mechanism?

- ▶ Just compare with the standard distribution mechanisms
 - ▶ **Swarmlinda should be able to improve the availability of the system**
- ▶ Here there are no
 - ▶ Assumptions about the behavior of the applications
 - ▶ Pre-defined distribution schema
 - ▶ Special scenarios to deal with failures in the nodes

Dealing With Openness

- ▶ The openness of a Linda system is dictated by how well it can deal with reconfigurations
- ▶ SwarmLinda may show adaptive behavior in reconfigurations we need
 - ▶ Tuples as ants
 - ▶ The tuple-space nodes as the environment
 - ▶ The scents as the state
- ▶ With the goal of maintaining similar tuples closed to each other one need to
 - ▶ Make tuples (already stored) sense their environment for tuple scents and template scents
 - ▶ Based on the strength of the scents the tuple may decide to move
- ▶ Note that we're now assuming that *out* also leave scent trails

Balancing the Movement of Tuples and Templates

- ▶ The issue here is related to “who” should be moving: tuples or templates
- ▶ At may make no sense to have template-ants moving around if the the producers of tuples know how to get to the consumer
 - ▶ In this case one might choose to leave the template-ants stationary while tuple-ants move towards it
- ▶ This may be achieved with the introduction of a producer-consumer scent ranging from -p to +p.
 - ▶ Positive values indicate that template ants were successfully matched with a tuple – the location is a producer of tuples
 - ▶ Negative values indicate that tuple ants were successfully matched with a template – the location is a consumer of tuples

Implementing SwarmLinda

- ▶ **Several practical issues need to be addressed when implementing SwarmLinda**
 - ▶ Here we describe our current approach and where we want to get
- ▶ **The issues are as follow**
 - ▶ Network topology
 - ▶ Separation of concerns
 - ▶ Movement of ants
 - ▶ Ant activity and the environment
 - ▶ Ants' lifecycle

Network Topology

- ▶ All the algorithms assume an environment
- ▶ How is this environment implemented?
- ▶ Currently
 - ▶ Nodes are organized in a (pseudo-)toroidal grid
 - ▶ The topology is fixed.
 - ▶ Updates are sent in a similar fashion as updates for routing tables in computer networks
- ▶ Full implementation
 - ▶ Nodes keep dynamic lists of neighbors that can be updated according to their “fitness” as a neighbor
 - ▶ How often does a node simply routed the ant to another node
 - ▶ This can help the creation of shortcuts
 - ▶ Neighbor relation is not symmetric and dynamic

Separation of Concerns

- ▶ In Linda terms this normally refers to the ability to create multiple spaces
- ▶ However at no point in the algorithms there is a reference to multiple tuple spaces
- ▶ The current implementation does not include the MTS concept at the Linda level
 - ▶ However Linda primitives still define a tuple space handle
 - ▶ The handle is just added as yet another element of the tuple
- ▶ In a full implementation
 - ▶ The tuple space name may be used as a differential scent
 - ▶ This will take advantage of the fact that tuples belonging to the same space belong together for some application specific purpose

Movement of Ants

- ▶ The movement of ants (tuple and template alike) are of prime importance to SwarmLinda
- ▶ In the current implementation we utilize two concepts
 - ▶ Scent strength of the neighbors
 - ▶ Simply a counter for the scents
 - ▶ Direction System
 - ▶ Pre-defined values to directions

30	40	27
10	↑	13
5	5	5

Direction System
sum = 135

1	1	1
6	↑	1
5	3	2

Scent Levels

30	40	27
60	↑	13
25	15	2

Resulting Values
sum = 212

27	13	5
40	←	5
30	10	5

Rotated System
sum = 135

- ▶ In a full implementation the above can be seen as list of pairs representing one direction $d = (ds, sl)$

Ant Activity and the Environment

- ▶ **Ants work in a cycle**
 - ▶ **Observe environment**
 - ▶ Observe and generate a vector of scents for a given location
 - ▶ **Plan change of the environment**
 - ▶ Decide the delta factor to be added to the current vector of values
 - ▶ The current approach also add one unit of scent this may be modified to add more according to some different criteria
 - ▶ **Change environment**
 - ▶ All delta vectors added give a delta matrix that is atomically added to the environment matrix
- ▶ **Evaporation of scents can use a similar approach where the values of the delta vector are negative**

Ants' Lifecycle

- ▶ How do ants die?
- ▶ Ants keep a value that is incremented at every step they take
 - ▶ This value is the ant life
- ▶ Not only this is used in the probability of an ant to drop the food (in case of out), it is also used in consumer primitives
- ▶ For consumer primitives, an ant dying consists of a failure mode
 - ▶ This is fine with *inp* and *rdp* but not for blocking primitives
- ▶ For the blocking primitives
 - ▶ Failure causes the ants to be placed in a sleep list – sleep may allow the configuration of the system to change
 - ▶ Too many sleeps can yield a recreation of the ant at the origin.
 - ▶ Too many recreations may cause a “warp”.

Conclusion

► What have been done

- We have described schemes for adapting swarm techniques to Linda
- These techniques provide a good alternative for standard approaches in Linda
- We have demonstrated that the implementation is very simple and requires very few ideas to be incorporated in the Linda system
- We have also discussed general approaches for future SwarmLinda implementations

► There is a lot to be learned on this arena

- Blocking as understood today may be hard to implement
- Experimental results are now need to validate our theoretical description and analysis